

Characterizing and Understanding the Differences Between GOES WF_ABBA and MODIS Fire Products



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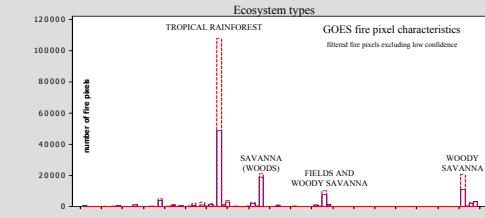
SATELLITE SIMILARITIES AND DIFFERENCES

- Orbit
 - Spatial coverage
 - Temporal coverage
 - Polar v Geostationary orbit
- Instrument design
 - Saturation thresholds
 - Spectral sensitivity
 - Resolution
- Fire detection algorithm
 - 4 μm temperature and 4 μm and 11 μm temperature difference thresholds
 - Dynamic contextual background calculations
 - Cloud, water, and land type masks
 - Surface emissivity, atmospheric attenuation, and solar reflectivity correction

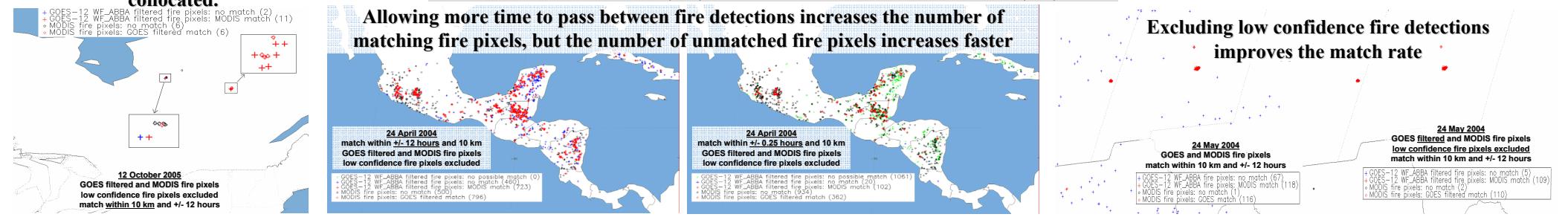
CONCLUSIONS

- Fire pixels with a match have different characteristics than fire pixels with no match
- Fire pixel characteristics can be used to forecast fire pixel matches
- Collocated fire pixels are not exactly collocated; spatial and temporal criteria is important

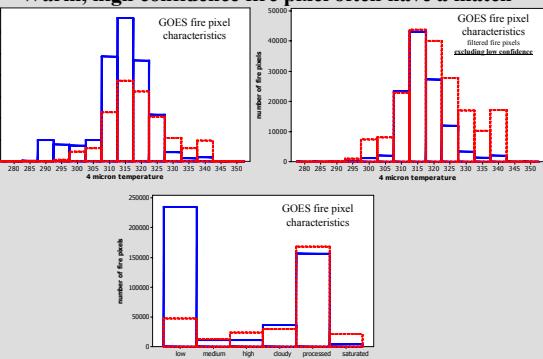
Different ecosystems are more likely to contain fire pixels with a match than other ecosystems



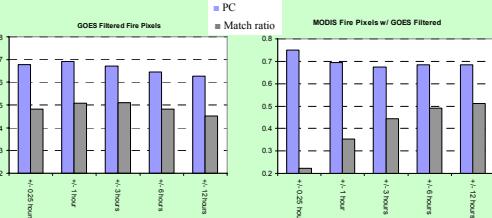
Allowing more time to pass between fire detections increases the number of matching fire pixels, but the number of unmatched fire pixels increases faster



Cool, low confidence fire pixels often go unmatched
Warm, high confidence fire pixel often have a match



Fire pixel characteristics can be used to forecast fire pixel matches



Discriminant analysis applies fire pixel characteristics to forecast if a fire pixel will have a matching pixel from another satellite fire product without referring to data from the other product.

PC – the number of correct forecasts compared to number of fire pixels

Match ratio – the number of fire pixels with a match compared to the number of fire pixels

Data Products

- GOES WF_ABBA version 6.0 ASCII fire data along with the filtered product where temporal filtering helps to screen false detections.
- MODIS fire product, collection 4.

Excluding low confidence fire detections improves the match rate

